

EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	2	"20060249486"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 11:04
L2	1	EP with "1617965"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 11:04
L3	1	1 and scanner	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 11:51
L4	1	1 and scanner with head	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 11:53
L5	1	1 and scanner near2 head	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 11:54
L6	1	1 and \$4stationar\$7	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 11:54
L7	0	1 and moving adj means	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 12:01
L8	0	1 and moving near2 means	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 12:51

L9	0	1 and moving with means	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 12:51
L10	2	1 and moving	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 12:51
L11	0	1 and moving with mean	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 12:51
L12	0	1 and mean	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 12:57
L13	211	219/121.63 and mean	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 12:58
L14	2	((("6204469") or ("4654505")).PN.	USPAT; USOCR	OR	OFF	2010/06/14 12:58
L15	29	("20010017291" "20020104833" "20020170889" "4162387" "4654505" "4973817" "5115115" "5359872" "6072149" "6153853" "6204469" "6211483" "6531675" "6822187" "6920375").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:03
L16	1	1 and (scanner mirror reflect\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:08

L17	1	1 and moving with ax? s	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:16
L18	7	(work workpiece piece component part) with (feed\$4 suppl\$5) same (movement move moving movable translat\$4 convey\$4) with multi\$4 adj2 ax?s same predetermin\$4 same (computer\$8 program\$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:23
L19	1	1 and transmission	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:36
L20	1	1 and beam with guide	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:41
L21	0	14 and robot with multiaxial\$4	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:51
L22	0	14 and robot with multi \$3 with (axis axes axial \$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:52
L23	0	14 and multi\$3 with (axis axes axial\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:52
L24	2	14 and (axis axes axial \$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 13:52
L25	1	1 and beam with switch	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 14:19

L26	1	1 and transmission with head	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 14:20
L27	12	workpiece with laser with weld\$4 and workpiece with (move \$1 moving movement movable moveable translat\$4) with (multi \$3 plural\$4) adj ax?s	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 14:26
L28	27	laser with weld\$4 and (move\$1 moving movement movable moveable translat\$4) with (multi\$3 plural\$4) adj ax?s with weld\$4	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 14:56
L29	19	laser with weld\$4 and (move\$1 moving movement movable moveable translat\$4) with (multi\$3 plural\$4) adj ax?s with weld\$4 and (pc computer program\$4)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/06/14 14:59

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